

YOLOv8을 사용한 객체 탐지

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- YOLOv8을 사용하기 위해 ultralytics 패키지를 설치 필요
- GPU의 유형 변경
 - 코랩 노트북 -> 런타임 -> 런타임 유형 변경 -> 하드웨어 가속기에서 GPU 선택
- YOLO (You Only Live Once)는 인기 있는 컴퓨터 비전 모델
- YOLO는 실시간 객체 탐지를 위한 매우 인기 있는 알고리즘으로, 영상이나 이미지에서 사람, 차량, 동물 등 다양한 객체를 빠르게 탐지하고 분류하는 데 사용됩니다.
- Ultralytics는 컴퓨터 비전 분야에서 특히 딥러닝을 기반으로 한 객체 탐지(object detection) 기술로 잘 알려진 회사.
 - YOLO 모델 배포: 이미지 및 비디오에서 객체를 탐지하는 YOLOv5 및 YOLOv8 모델을 오픈소스로 제공.

v1에서 v9까지: 간략한 역사

- 2015 : YOLOv1 : 단일 단계 객체 감지 모델 도입
- 2016 : YOLOv2 : 고속 작동 (67-40FPS)
: 9000+ 객체 범주 감지
- 2018 : YOLOv3 : 효과적인 백본 네트워크
: 다중 앵커, 다중 규모 특징 추출
- 2020 : YOLOv4 : 모자이크 데이터 증대 기술 도입
- 2021 : YOLOv5 : 하이퍼파라미터 최적화
: 통합 실험 추적
- 2022 : YOLOv6 : 오픈 소스화
: 자가 증류 전략, AAT 전략 도입
- 2022 : YOLOv7 : 속도와 정확성 향상
: 당시 가장 빠른 객체 감지 모델
- 2023 : YOLOv8 : 다중 작업 지원
: 새로운 아키텍처 도입
- 2024 : YOLOv9 : 프로그래머블 그래디언트 정보 도입
: 더 작은 모델로 높은 성능 달성

```
In [1]: !pip install ultralytics
```

Collecting ultralytics

Downloading ultralytics-8.2.93-py3-none-any.whl.metadata (41 kB)

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Requirement already satisfied: numpy<2.0.0,>=1.23.0 in /usr/local/lib/python3.10/dist-packages (from ultralytics) (1.26.4)
 Requirement already satisfied: matplotlib>=3.3.0 in /usr/local/lib/python3.10/dist-packages (from ultralytics) (3.7.1)
 Requirement already satisfied: opencv-python>=4.6.0 in /usr/local/lib/python3.10/dist-packages (from ultralytics) (4.10.0.84)
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 Requirement already satisfied: filelock in /usr/local/lib/python3.10/dist-package

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s (from torch>=1.8.0->ultralytics) (3.16.0)
Requirement already satisfied: typing-extensions>=4.8.0 in /usr/local/lib/python
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Requirement already satisfied: six>=1.5 in /usr/local/lib/python3.10/dist-package
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Requirement already satisfied: MarkupSafe>=2.0 in /usr/local/lib/python3.10/dist-
packages (from jinja2->torch>=1.8.0->ultralytics) (2.1.5)
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Downloading ultralytics_thop-2.0.6-py3-none-any.whl (26 kB)
Installing collected packages: ultralytics-thop, ultralytics
Successfully installed ultralytics-8.2.93 ultralytics-thop-2.0.6
```

```
In [5]: from ultralytics import YOLO
import cv2 # OpenCV 라이브러리를 불러오기
from google.colab.patches import cv2_imshow # from google.colab.patches import

# YOLOv8 모델 로드
model = YOLO('yolov8n.pt') # YOLOv8의 경량 모델

# 이미지 로드
img = cv2.imread('Dog_rawPixel01.jpg')

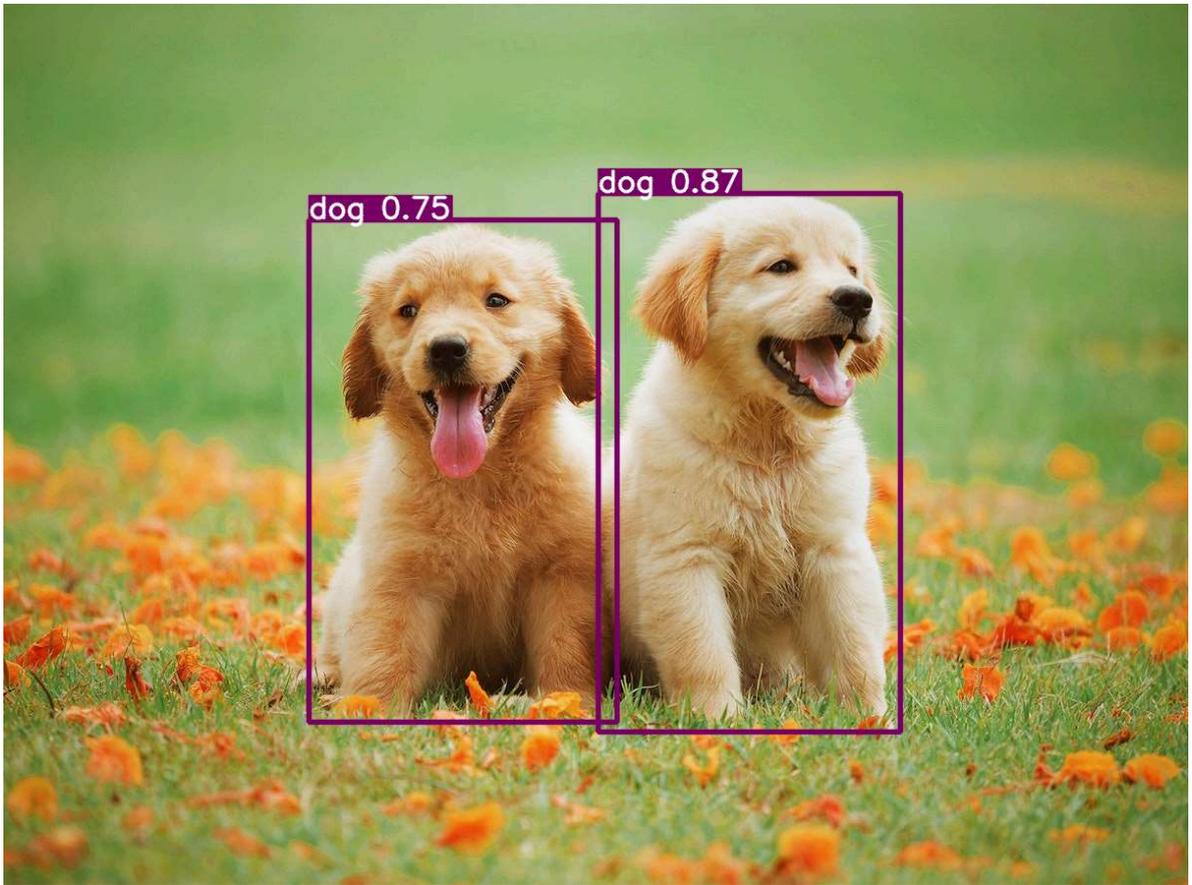
# 객체 탐지
# 로드된 YOLOv8 모델을 사용하여 이미지에서 객체를 탐지합니다. results 변수에는 탐
results = model(img)

# 결과 시각화
# plot() 함수는 탐지된 객체 주변에 경계 상자를 그려 이미지를 반환
img_with_detections = results[0].plot() # 첫 번째 결과를 시각화

# 결과 이미지 표시
cv2_imshow(img_with_detections)
```

0: 480x640 2 dogs, 42.6ms

Speed: 2.7ms preprocess, 42.6ms inference, 1.2ms postprocess per image at shape (1, 3, 480, 640)



```
In [ ]: from ultralytics import YOLO
import requests
import cv2
import numpy as np
from google.colab.patches import cv2_imshow

# 웹에서 이미지 가져오기
url = 'https://images.unsplash.com/photo-1503256207526-0d5d80fa2f47?q=80&w=1286&
resp = requests.get(url).content
img_array = np.asarray(bytearray(resp), dtype=np.uint8)
img = cv2.imdecode(img_array, cv2.IMREAD_COLOR)

# YOLOv8 모델 로드
model = YOLO('yolov8n.pt') # YOLOv8의 경량 모델

# 이미지 로드
# img = cv2.imread('path/to/your/image.jpg')

# 객체 탐지
results = model(img)

# 결과 시각화
img_with_detections = results[0].plot() # 첫 번째 결과를 시각화

# 결과 이미지 표시
cv2_imshow(img_with_detections)
```

Output hidden; open in <https://colab.research.google.com> to view.

```
In [ ]: # https://images.unsplash.com/reserve/oIpwxeeSPy1cnwYpqJ1w_Dufer%20Collateral%20
```

```
In [ ]:
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